

2023 Competition on Computational Astrophysics Problem I

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2023 Winter School on Numerical Relativity and Gravitational Waves

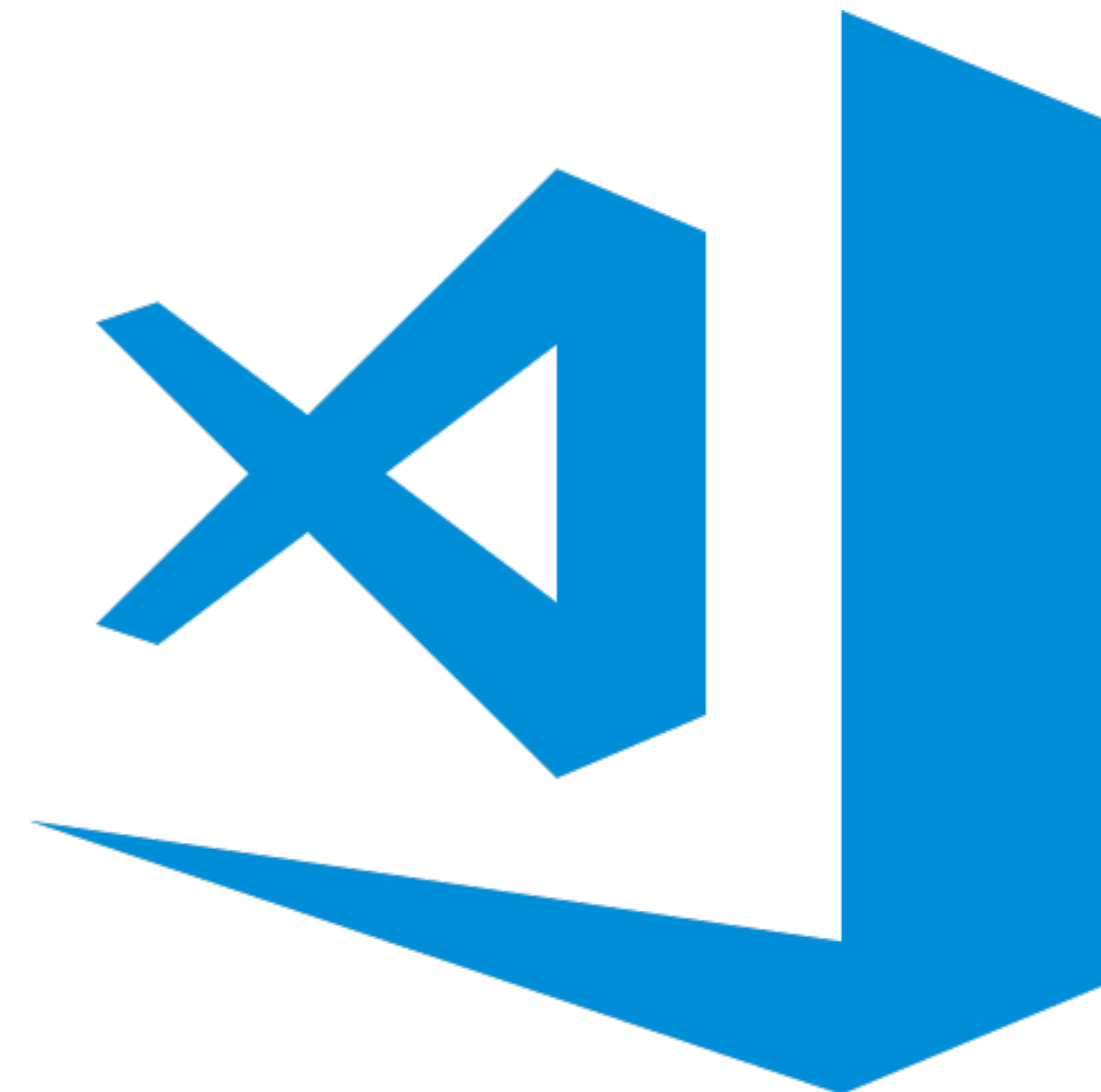
Overview

- Development Routine
 - IDE: VS Code
 - Test: Jupyter Notebook
 - Submission: Git
 - Code Review
- Numerical Analysis
 - Finite Difference Method
 - Iterative Method
 - Multigrid Method
- Problems

Development Routine

VS Code

- IDE: Integrated Development Environment
- It can open the filesystem of remote server through SSH.
- Supporting OS: Windows / Mac / Linux
- <https://code.visualstudio.com>



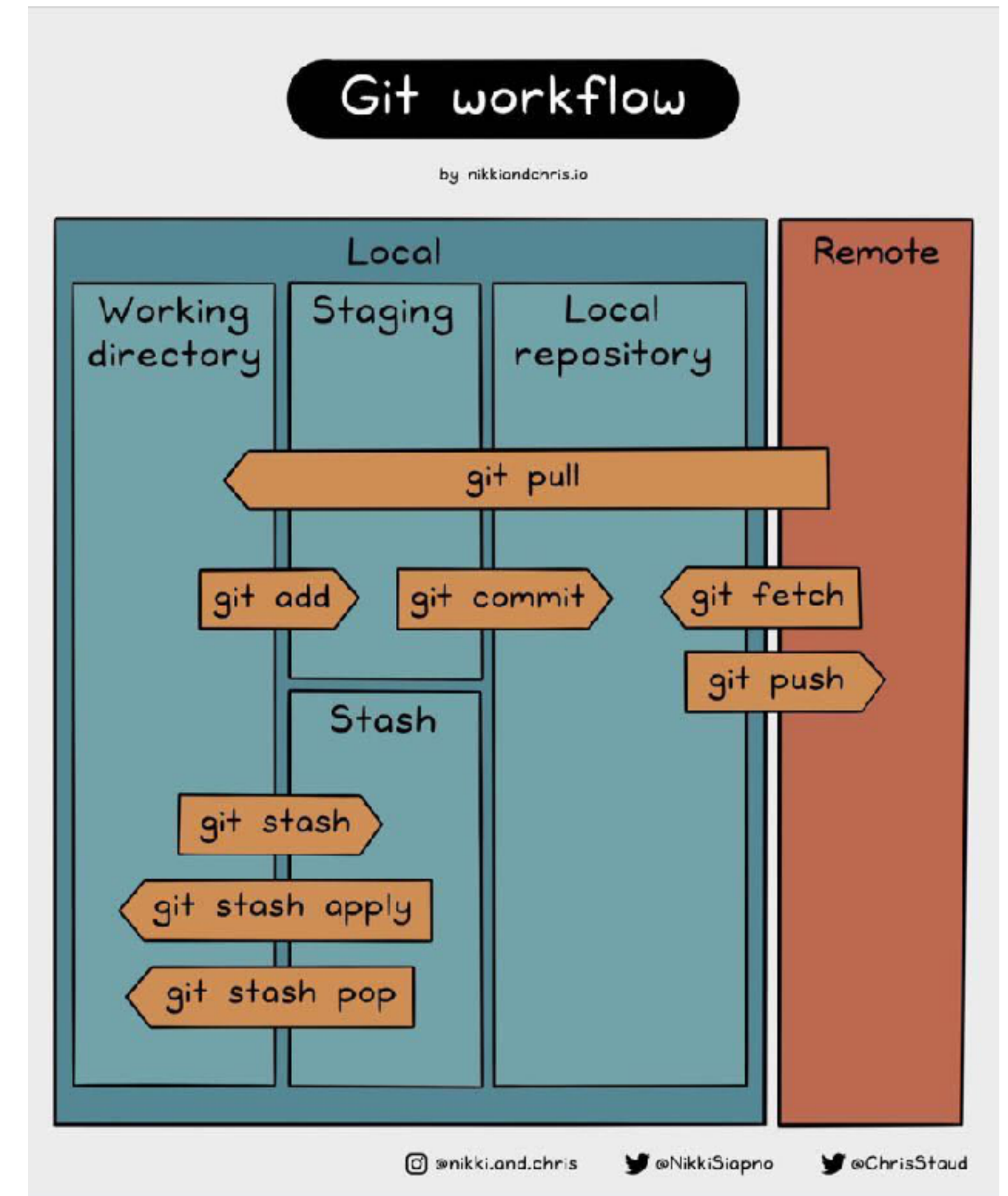
Jupyter Notebook

- An interactive interface for Python through web
- In general, you can use any web browser in any OS.
- We will use jupyter notebook in VS Code to test codes.

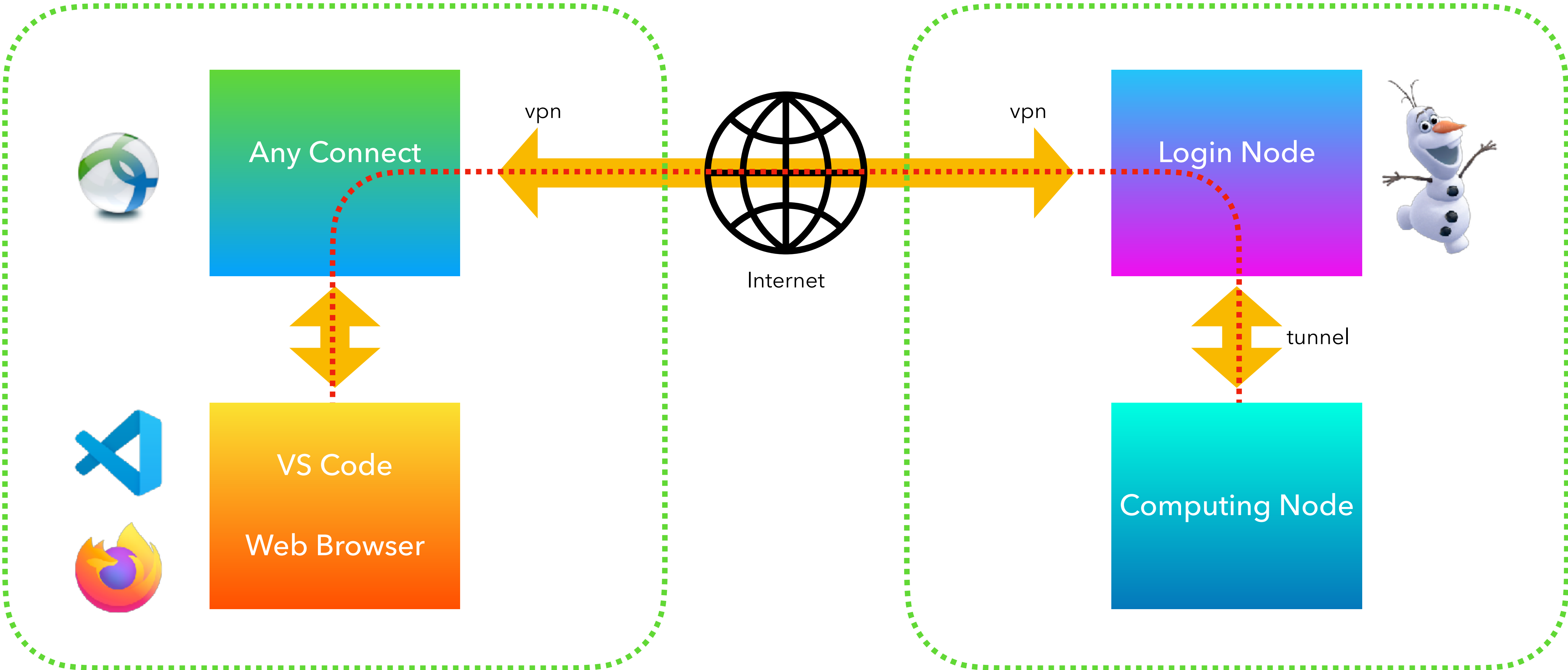


Git

- Version Control System
- Distribution of example code and submission of answer code are conducted by git.



Network Diagram



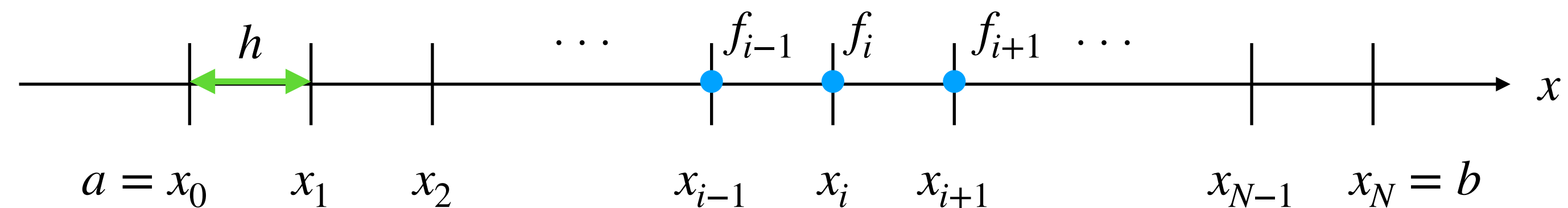
Computer in UNIST Learning Commons

IBS Supercomputing Cluster

Numerical Analysis: Finite Difference Method

Discretization

- For function $f(x) : [a, b] \rightarrow \mathbb{R}$
- Uniform discretization
 - $x_i = ih$ for integer $0 \leq i \leq N$ and $h = (b - a)/N$ where N is the number of cells
 - $f_i = f(x_i)$



Derivatives by Finite Difference Method (FDM)

- Taylor Expansions

- $f_{i+1} = f(x_{i+1}) = f(x_i + h) = f(x_i) + hf'(x_i) + \frac{1}{2}h^2f''(x_i) + \frac{1}{3!}h^3f^{(3)}(x_i) + \frac{1}{6!}h^4f^{(4)}(x_i) + O(h^5)$

- $f_{i-1} = f(x_{i-1}) = f(x_i - h) = f(x_i) - hf'(x_i) + \frac{1}{2}h^2f''(x_i) - \frac{1}{3!}h^3f^{(3)}(x_i) + \frac{1}{6!}h^4f^{(4)}(x_i) + O(h^5)$

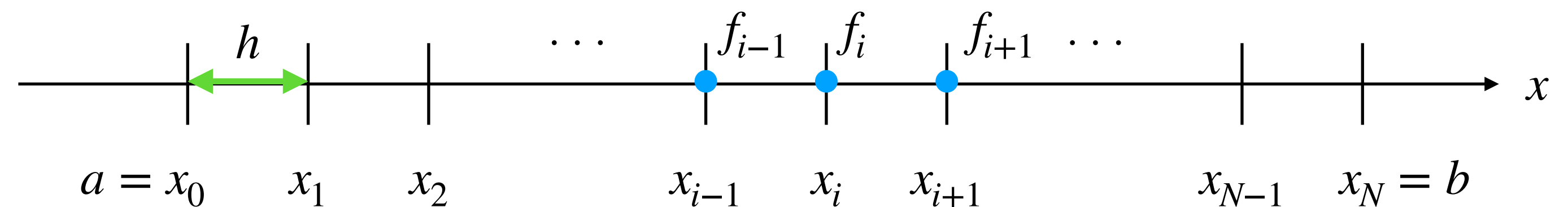
- First-Order FDM

- $f'(x_i) = \frac{1}{h} (f_{i+1} - f_i) + O(h)$

- Second-Order FDM

- $f'(x_i) = \frac{1}{2h} (f_{i+1} - f_{i-1}) + O(h^2)$

- $f''(x) = \frac{1}{h^2} (f_{i+1} + f_{i-1} - 2f_i) + O(h^2)$



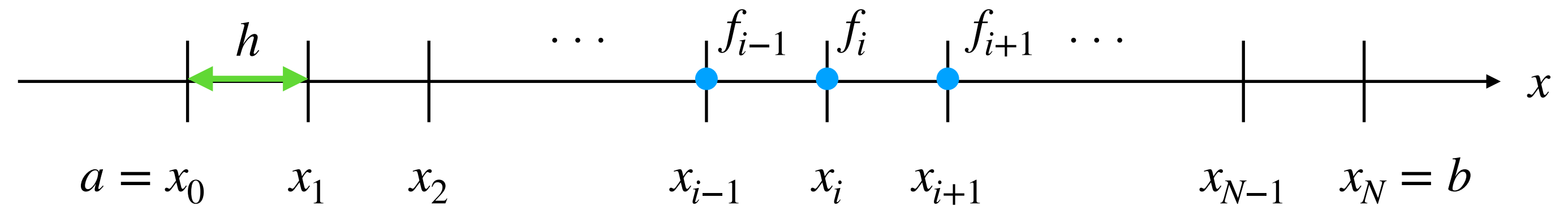
Elliptic PDE as a Sparse Matrix

- Simple Problem

- Given $\frac{d^2f}{dx^2} = f''(x) = \rho(x)$ with the homogeneous boundary condition: $f(a) = f(b) = 0$, solve $f(x)$

- Second-Order Finite Difference Method

- $\frac{1}{h^2} (f_{i+1} + f_{i-1} - 2f_i) \simeq \rho_i$



- In sparse matrix

- $$\frac{1}{h^2} \begin{bmatrix} -2 & 1 & & & & & \\ 1 & -2 & 1 & & & & \\ & & 1 & -2 & \ddots & & \\ & & & \ddots & \ddots & & \\ & & & & & -2 & 1 \\ & & & & & 1 & -2 \end{bmatrix} \begin{bmatrix} f_1 \\ f_2 \\ \vdots \\ f_{N-1} \end{bmatrix} = \begin{bmatrix} \rho_1 \\ \rho_2 \\ \vdots \\ \rho_{N-1} \end{bmatrix} \quad \rightarrow \quad \mathbf{A}f = \rho$$

- In principle, we can get f_i by the inverse of the above matrix.

Numerical Analysis: Iterative Method

Difficulties on Solving Linear System

- Linear System

$$\bullet \frac{1}{h^2} \begin{bmatrix} -2 & 1 & & & \\ 1 & -2 & 1 & & \\ & 1 & -2 & \ddots & \\ & & \ddots & \ddots & \\ & & & -2 & 1 \\ & & & 1 & -2 \end{bmatrix} \begin{bmatrix} f_1 \\ f_2 \\ \vdots \\ f_{N-1} \end{bmatrix} = \begin{bmatrix} \rho_1 \\ \rho_2 \\ \vdots \\ \rho_{N-1} \end{bmatrix}$$

- $Af = \rho \rightarrow f = A^{-1}\rho$
- Matrix inversion of large matrix requires a tremendous amount of calculation and storage space. Eventually solving in this way is almost impossible.
- We seek an approximate solution by iterative method instead of exact solution of the linear system.
- The error of approximate solution can be controlled as desired.

Gauss-Seidel Method

- From the FDM

- $\frac{1}{h^2} (f_{i+1} + f_{i-1} - 2f_i) \simeq \rho_i$

- We get relaxation as

- $f_i \simeq \frac{1}{2} (f_{i+1} + f_{i-1} - \rho_i h^2)$

- We set iterative algorithm as

- For a number of steps

- For $i \in [1, N)$

- $f_i \leftarrow \frac{1}{2} (f_{i+1} + f_{i-1} - \rho_i h^2)$

i	0	...	i-1	i	i+1	...	N
f	0	...	f[i-1]	f[i]	f[i+1]	...	0
rho		...		rho[i]		...	

Jacobian Method

- For a number of steps
 - For $i \in [1, N)$
 - $f_i^{\text{new}} \leftarrow \frac{1}{2} (f_{i+1} + f_{i-1} - \rho_i h^2)$
 - $\text{switch}(f_i^{\text{new}}, f_i)$

i	0	...	i-1	i	i+1	...	N
f	0	...	f[i-1]	f[i]	f[i+1]	...	0
f_new		...		f_new[i]		...	
rho		...		rho[i]		...	

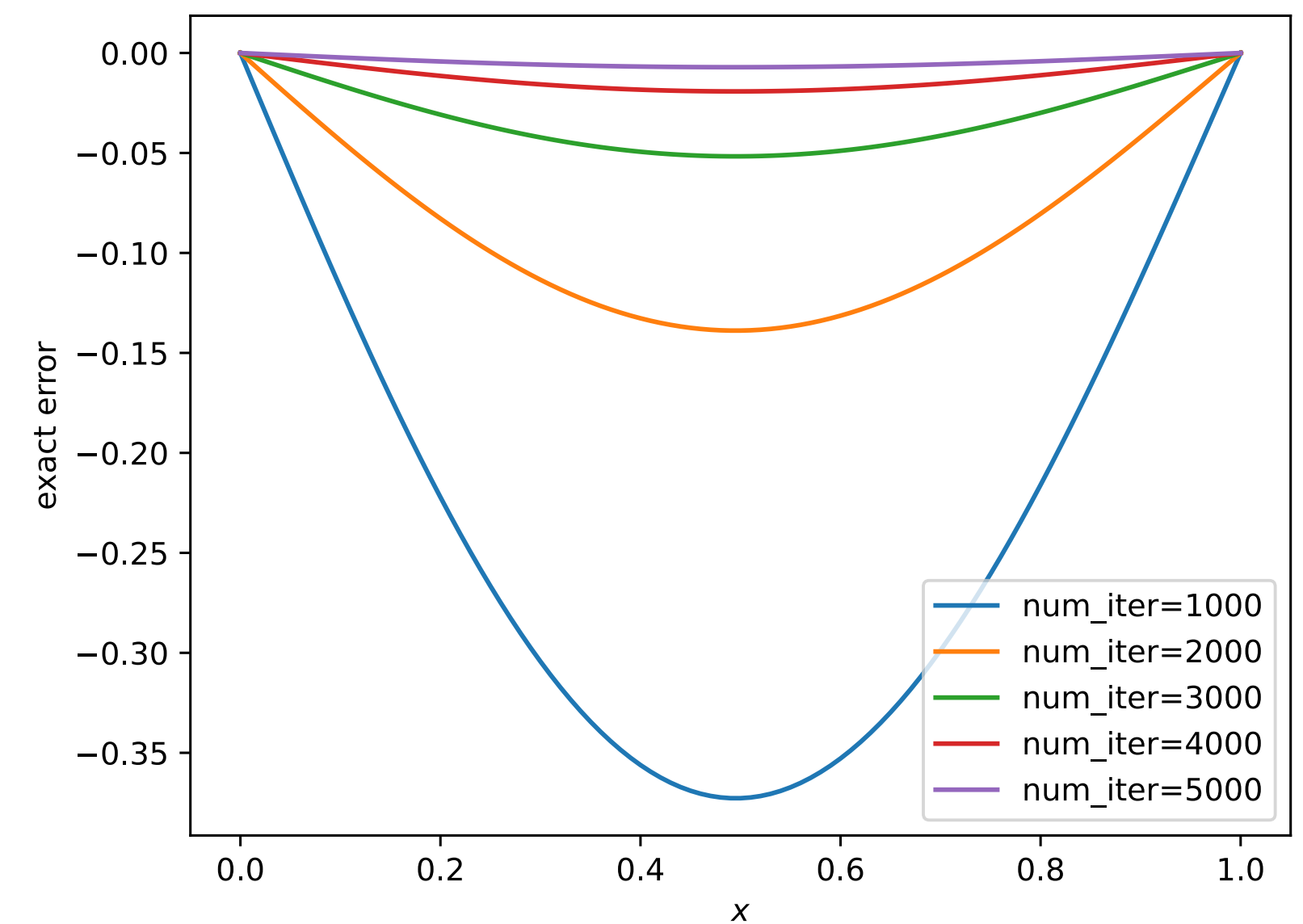
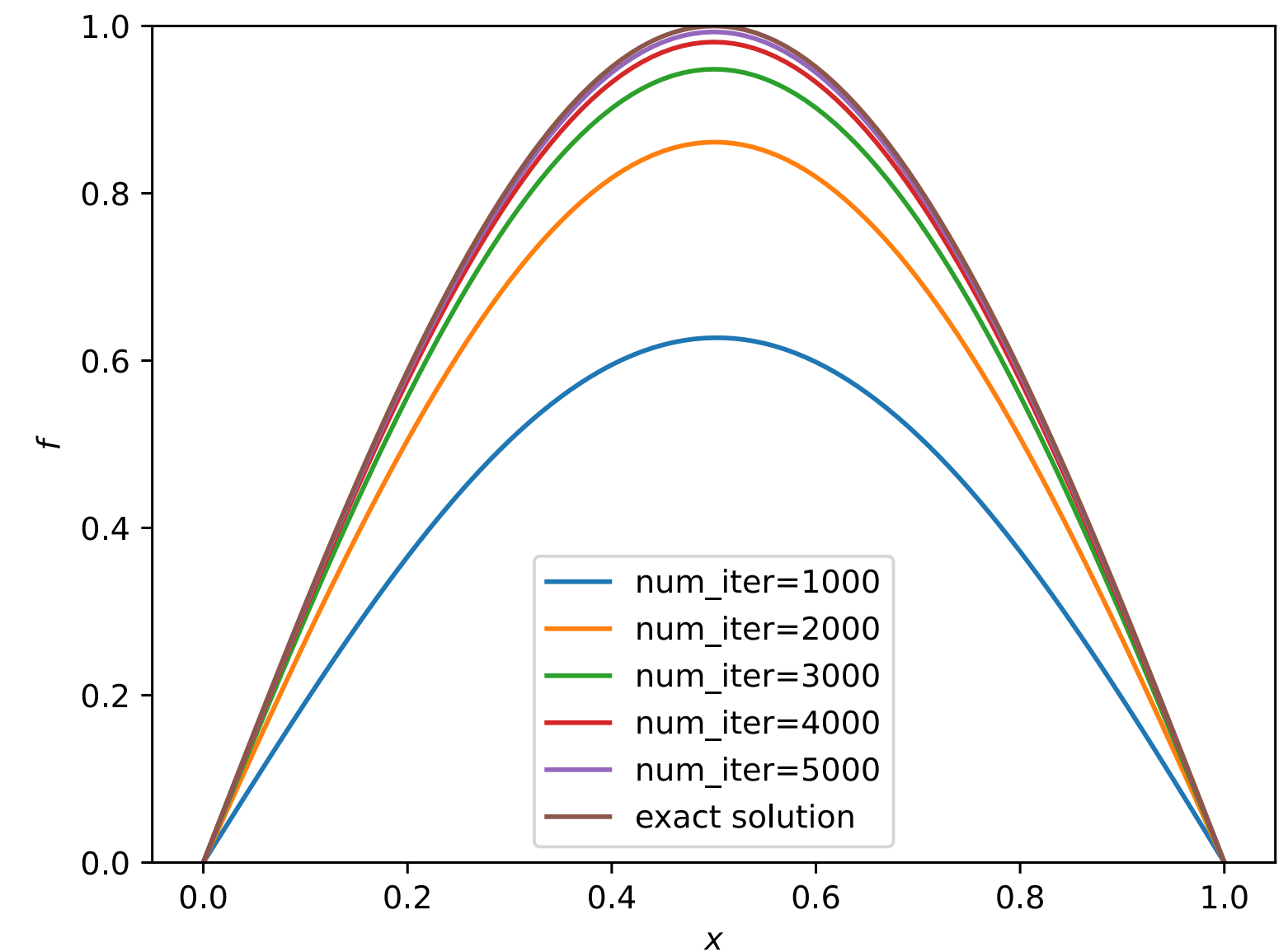
Red-Black Ordering Method

- For a number of steps
 - For $i \in [1, N)$ by step 2
 - $f_i \leftarrow \frac{1}{2} (f_{i+1} + f_{i-1} - \rho_i h^2)$
 - For $i \in [2, N)$ by step 2
 - $f_i \leftarrow \frac{1}{2} (f_{i+1} + f_{i-1} - \rho_i h^2)$

i	0	1	2	...	N-2	N-1	N
f	0	0
rho		

Result

- Example
 - $\rho(x) = -\pi^2 \sin(\pi x)$
- Exact Solution
 - $f(x) = \sin(\pi x)$
- Number of Cells
 - $N = 100$
- As the number of iteration increases, the numerical solution converges to $\sin(\pi x)$.



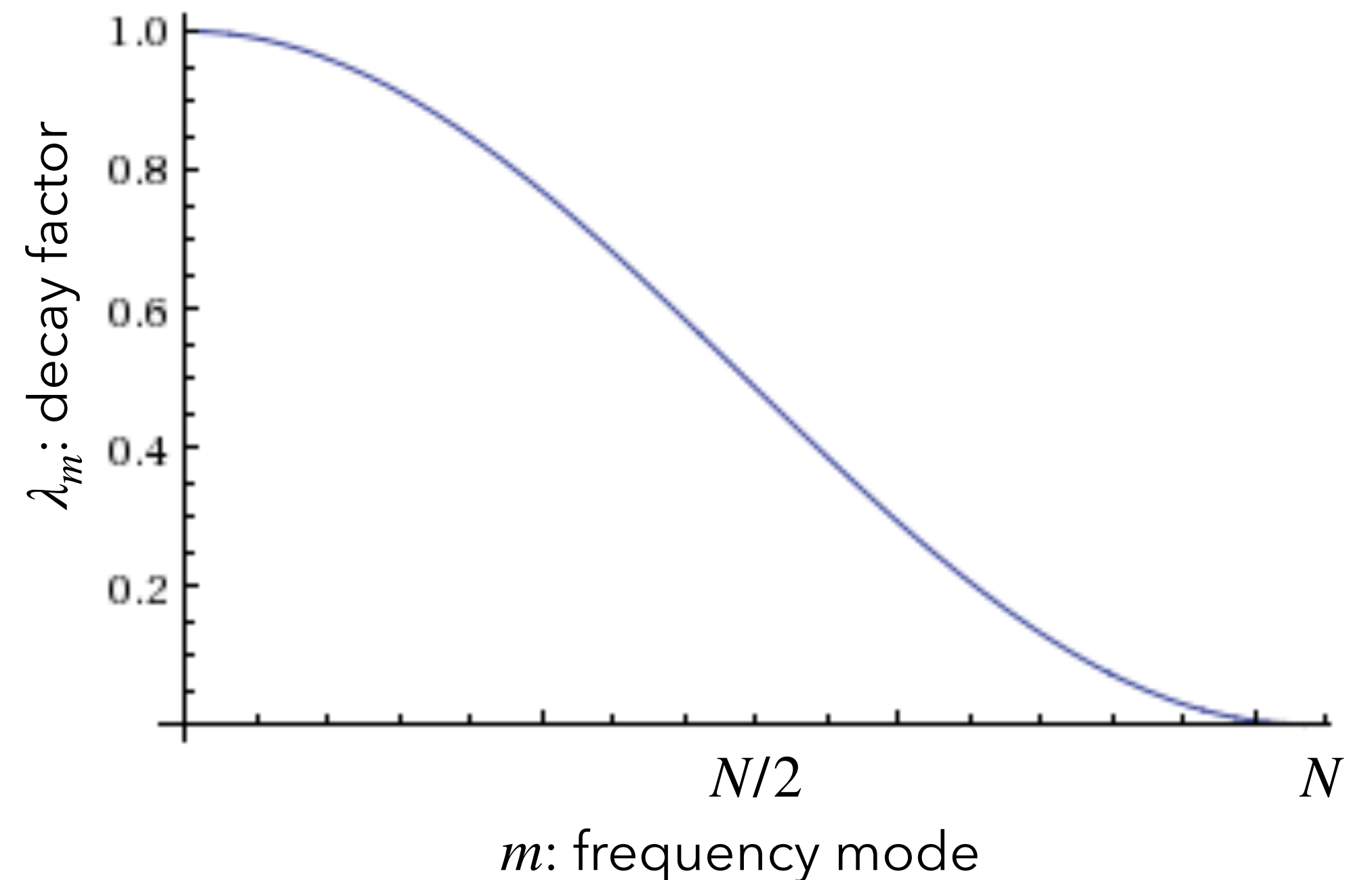
Residual

- How to measure the convergence when we don't know an exact solution?
- Residual
 - $r = \rho - \mathbf{A}f$ goes to 0 when f converges to the solution
- Exact error
 - $e = \bar{f} - f$ where \bar{f} is the exact solution
- Relation between the exact error and the residual
 - $\mathbf{A}e = r$ because $\mathbf{A}\bar{f} = \rho$
- Solving $\mathbf{A}e = r$ is equivalent to solving the original equation $\mathbf{A}f = \rho$

Numerical Analysis: Multigrid

Difficulties on High Frequency Modes

- Residual-Error equation
 - $Ae = r$
- An error of m mode is decay by the factor λ_m
 - $(\lambda_m)^n$ where n is the number of iterations
- Can we devise a method that efficiently decay low mode errors?
- How about to use a coarse grid?

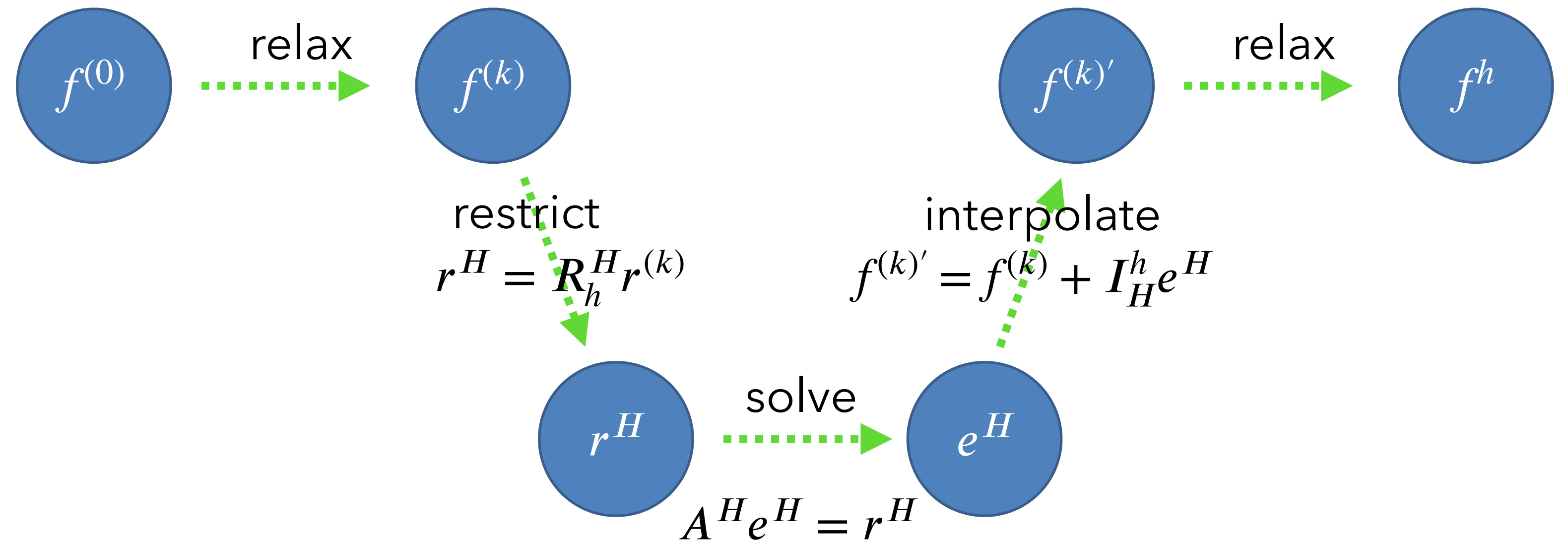
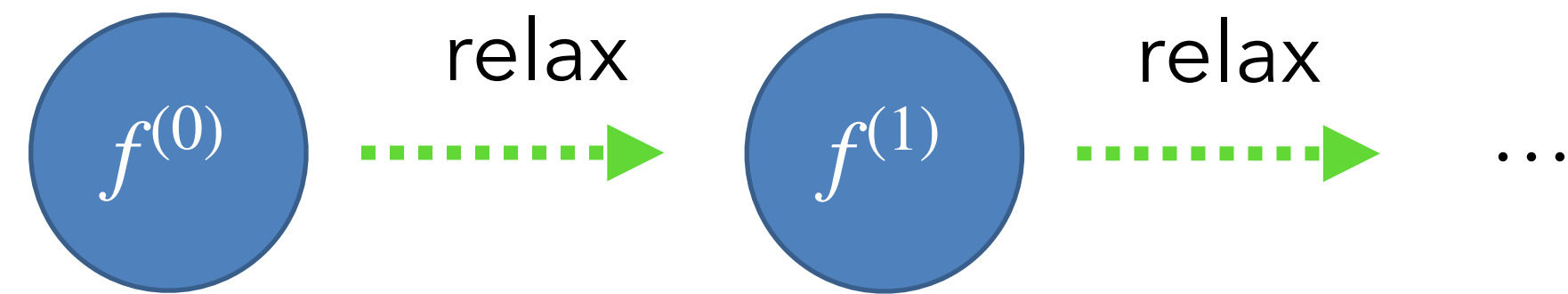


Decay factors for frequency modes
in the iterative method

Two-Grid Method

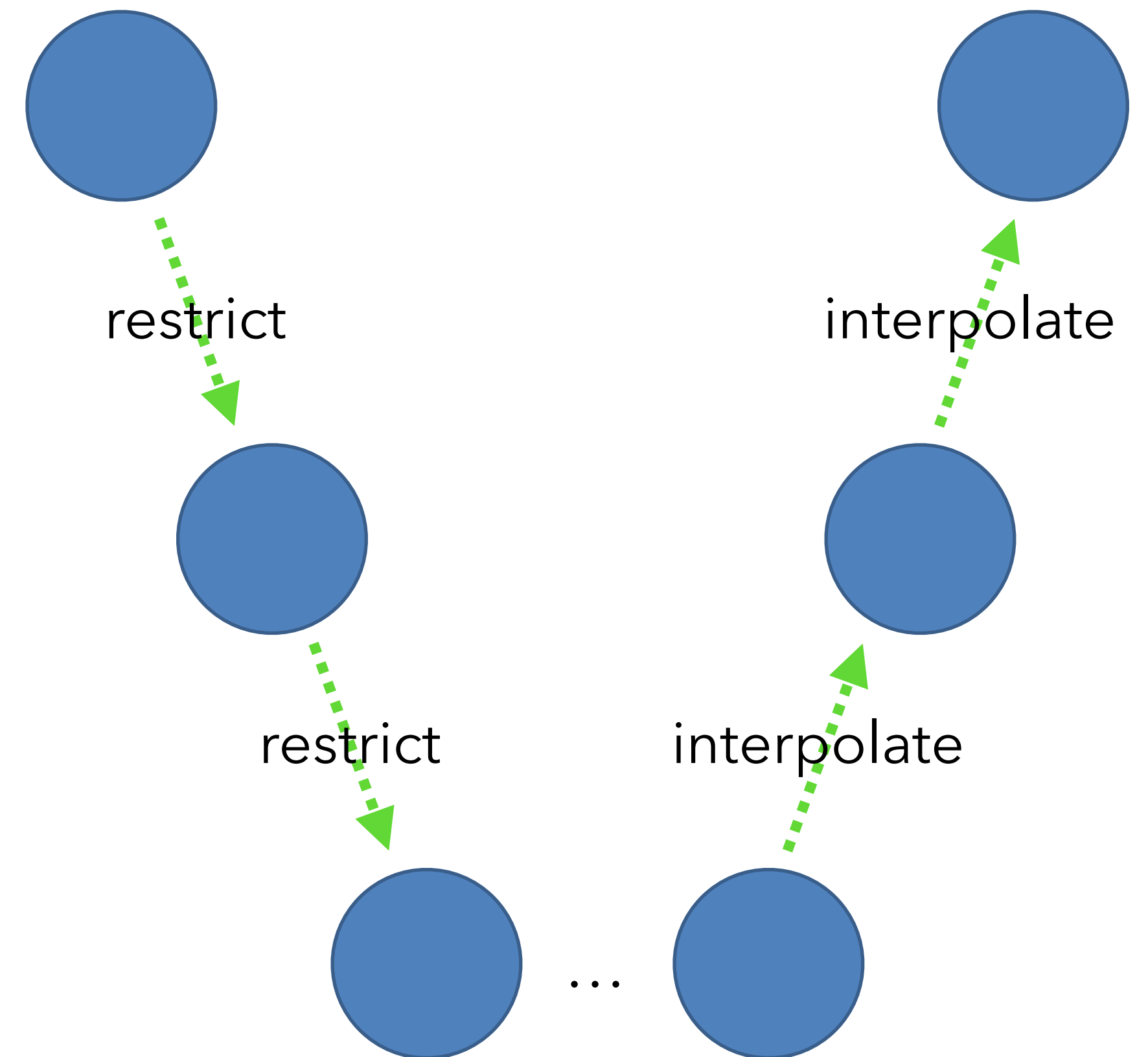
- TwoGrid(f, ρ)

- relax (f, ρ)
- $r \leftarrow$ residual of f
- $r^H \leftarrow$ restriction of r
- $e^H \leftarrow 0$
- solve $Ae^H = r^H$
- $e \leftarrow$ interpolation of e^H
- $f \leftarrow f + e$
- relax (f, ρ)



Multigrid Method

- Recursive two-grid method
- In the most coarse grid, only once iteration solves exactly.
- $\text{MultiGrid}(f, \rho, n)$
 - if $n = 1$ then relax (f, ρ) and return
 - relax (f, ρ)
 - $r \leftarrow$ residual of f
 - $r^H \leftarrow$ restriction of r
 - $e^H \leftarrow 0$
 - $\text{MultiGrid}(e^H, r^H, n - 1)$
 - $e \leftarrow$ interpolation of e^H
 - $f \leftarrow f + e$
 - relax (f, ρ)



Linear Interpolation

- Interpolation (f^h, f^H)

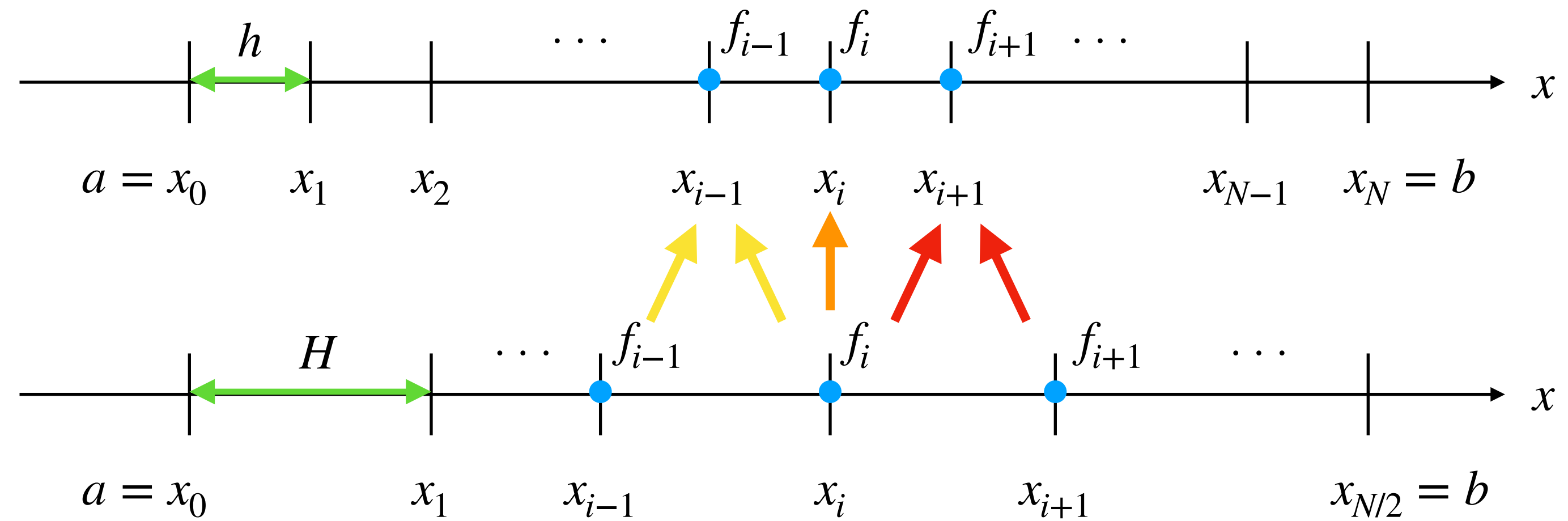
- For $i \in [1, N)$

- If i is even then

- $f_i^h \leftarrow f_{i/2}^H$

- else

- $f_i^h \leftarrow \frac{1}{2} \left(f_{\lfloor i/2 \rfloor}^H + f_{\lfloor i/2 \rfloor + 1}^H \right)$



Full Weighting Restriction

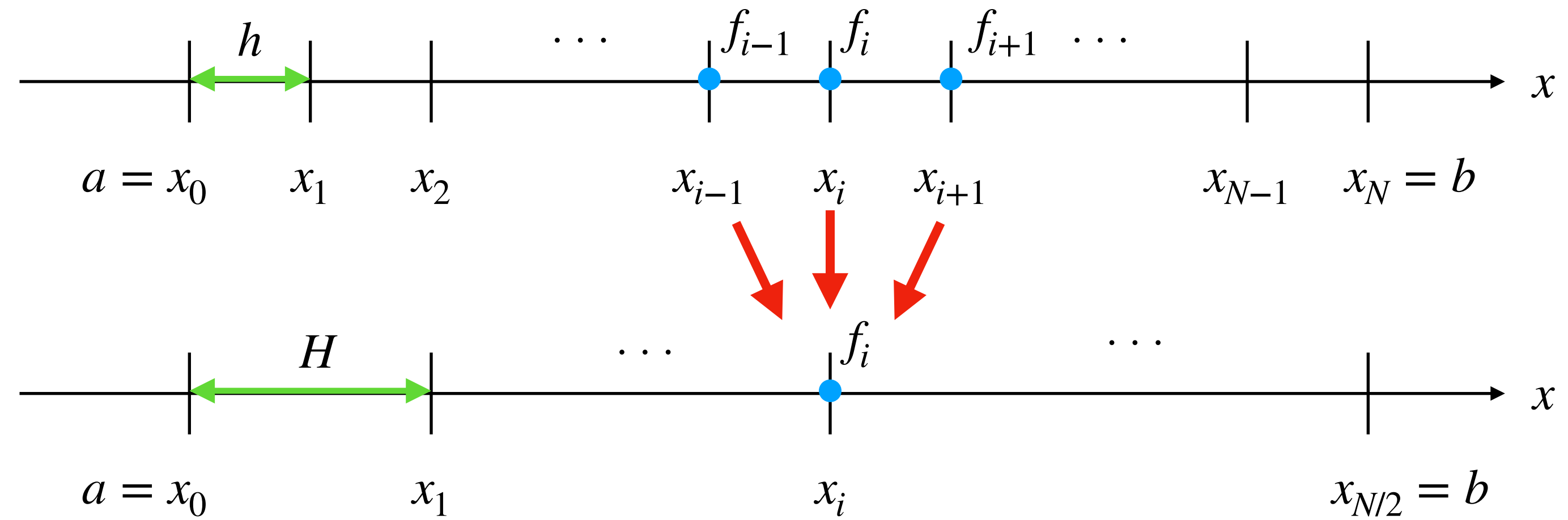
- Restriction (f^H, f^h)

- For $i \in [1, N)$

- $f_i^h \leftarrow \frac{1}{4} f_{2i-1}^H + \frac{1}{2} f_{2i}^H + \frac{1}{4} f_{2i+1}^H$

- It is adjoint to the interpolation in the sense

- $\langle a^H | R_h^H b^h \rangle = \langle b^h | I_H^h a^H \rangle$



Problem I

Problem I

- 1-1. Iterative Relaxation: 20 pt
- 1-2. Interpolation: 10 pt
- 1-3. Restriction: 10 pt
- 1-4. Multigrid Method: 30 pt
- 1-5. Black Hole: 30 pt

Let's start the competition!!